



Specification document of AD22100A

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|------------------------|---|-------------|---|
| Component manufacturer | Analog Devices | | |
| Model number | AD22100A | | |
| Datasheets | AD22100 (REV. D) (analog.com) | | |
| Specification Ver | 01.00.00 | Oct 03,2022 | New release |
| | 01.00.01 | Oct 18,2022 | Corrected license content Application item add |
| Documentation provided | Rui Long Lab Inc. https://rui-long-lab.com/ | | |

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|--|---|
| 1. Component datasheet | 2 |
| 2. Component Software IF specification | 3 |
| 3. File Structure and Definitions | 5 |

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1. Component datasheet

| | |
|---------------------------------------|---|
| Temperature accuracy | $\pm 2.0^{\circ}\text{C}$ (-40°C to $+85^{\circ}\text{C}$) |
| Range of power supply voltage (Vdd) | 4.0 to 6.5[V] |
| Output voltage (Vout) | Linear $22.5 \times \text{Vdd}/5$ [mV/ $^{\circ}\text{C}$] Typ. Vdd = 5.0 [V] -40 [$^{\circ}\text{C}$] 0.475[V] Typ. 85 [$^{\circ}\text{C}$] 3.288 [V] Typ. |
| Calculation | $\text{Vout} = (\text{Vdd}/5\text{ V}) \times (1.375\text{ V} + 22.5\text{ mV}/^{\circ}\text{C} \times \text{Ta})$ $\text{Ta} = (\text{Vout} / (\text{Vdd}/5\text{V}) - 1.375\text{V}) / 22.5\text{ mV}/^{\circ}\text{C}$ |
| Applications | IoT etc <ul style="list-style-type: none">• HVAC systems• System temperature compensation• Board level temperature sensing• Electronic thermostats Automotive |

2. Component Software IF specification

The software interface specifications based on the AD22100A component specifications are as follows.

The voltage value-to-physical value conversion equation is a linear conversion equation as shown in the equation below.

ADC value to voltage value conversion formula

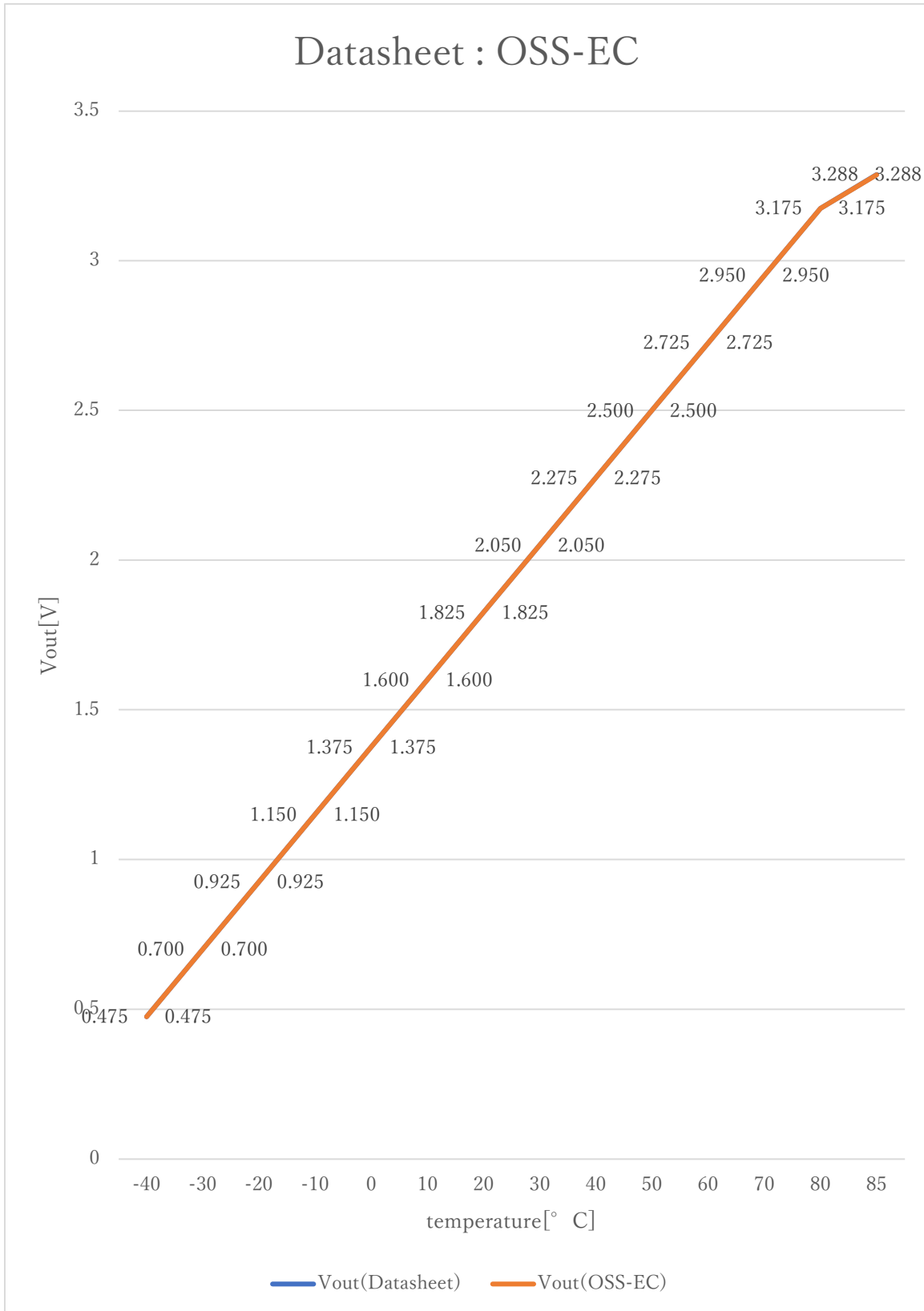
$$v_i = (a_i \times i_{ADC_vdd}) / 2^{i_{ADC_bit}} \quad [V]$$

Voltage value to physical value conversion formula

$$y = (v_i - i_{AD22100A_xoff}) / i_{AD22100A_gain} + i_{AD22100A_yoff} \quad [^{\circ}C]$$

$$i_{AD22100A_min} \leq y \leq i_{AD22100A_max}$$

| | |
|--|---|
| <code>a_i</code> | A/D conversion value |
| <code>v_i</code> | Sensor output voltage value [V] |
| <code>i_{ADC_vdd}</code> | Sensor supply voltage value [V] |
| <code>i_{ADC_bit}</code> | A/D conversion bit length |
| <code>y</code> | Temperature value [°C] |
| <code>#define i_{AD22100A_xoff}</code> | <code>(1.375F*(i_{ADC_vdd}/5.0))</code> // X offset [V] |
| <code>#define i_{AD22100A_yoff}</code> | <code>0.0F</code> // Y offset [°C] |
| <code>#define i_{AD22100A_gain}</code> | <code>(0.0225F*(i_{ADC_vdd}/5.0))</code> // Gain [V/°C] |
| <code>#define i_{AD22100A_max}</code> | <code>85.0F</code> // Temperature Max [°C] |
| <code>#define i_{AD22100A_min}</code> | <code>-40.0F</code> // Temperature Min [°C] |



3. File Structure and Definitions

AD22100A.h

```
#include "user_define.h"

// Components number
#define iAD22100A          106U          // Analog devices AD22100A

// AD22100A System Parts definitions
#define iAD22100A_xoff    (1.375F*(iADC_vdd/5.0)) // X offset [V]
#define iAD22100A_yoff    0.0F // Y offset [°C]
#define iAD22100A_gain    (0.0225F*(iADC_vdd/5.0)) // Gain [V/°C]
#define iAD22100A_max     85.0F // Temperature Max [°C]
#define iAD22100A_min     -40.0F // Temperature Min [°C]

extern const tbl_adc_t tbl_AD22100A;
```

AD22100A.cpp

```

#include      "AD22100A.h"

#if      iAD22100A_ma == iSMA                // Simple moving average filter
static float32 AD22100A_sma_buf[iAD22100A_SMA_num];
static const sma_f32_t AD22100A_Phy_SMA =
{
    iInitial ,                               // Initial state
    iAD22100A_SMA_num ,                      // Simple moving average number & buf size
    0U ,                                       // buffer position
    0.0F ,                                     // sum
    &AD22100A_sma_buf[0]                     // buffer
};

#elif      iAD22100A_ma == iEMA              // Exponential moving average filter
static const ema_f32_t AD22100A_Phy_EMA =
{
    iInitial ,                               // Initial state
    0.0F ,                                    // Xn-1
    iAD22100A_EMA_K                           // Exponential smoothing factor
};

#elif      iAD22100A_ma == iWMA              // Weighted moving average filter
static float32 AD22100A_wma_buf[iAD22100A_WMA_num];
static const wma_f32_t AD22100A_Phy_WMA =
{
    iInitial ,                               // Initial state
    iAD22100A_WMA_num ,                      // Weighted moving average number & buf size
    0U ,                                       // buffer poition
    iAD22100A_WMA_num * (iAD22100A_WMA_num + 1)/2 , // kn sum
    &AD22100A_wma_buf[0]                     // Xn buffer
};

#else                                         // Non-moving average filter
#endif

#define iDummy_adr      0xffffffff           // Dummy address

```

```
const tbl_adc_t tbl_AD22100A =
{
    iAD22100A          ,
    iAD22100A_pin     ,
    iAD22100A_xoff    ,
    iAD22100A_yoff    ,
    iAD22100A_gain    ,
    iAD22100A_max     ,
    iAD22100A_min     ,
    iAD22100A_ma      ,

    #if iAD22100A_ma == iSMA // Simple moving average filter
        &AD22100A_Phy_SMA    ,
        (ema_f32_t*) iDummy_adr ,
        (wma_f32_t*) iDummy_adr
    #elif iAD22100A_ma == iEMA // Exponential moving average filter
        (sma_f32_t*) iDummy_adr ,
        &AD22100A_Phy_EMA    ,
        (wma_f32_t*) iDummy_adr
    #elif iAD22100A_ma == iWMA // Weighted moving average filter
        (sma_f32_t*) iDummy_adr ,
        (ema_f32_t*) iDummy_adr ,
        &AD22100A_Phy_WMA
    #else // Non-moving average filter
        (sma_f32_t*) iDummy_adr ,
        (ema_f32_t*) iDummy_adr ,
        (wma_f32_t*) iDummy_adr
    #endif

};
```